

# CrossLink-NX ROI User Tracking Using VVML Board Demonstration

# **User Guide**



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# **Acronyms in This Document**

A list of acronyms used in this document.

Acronym	Definition
FPGA	Field-Programmable Gate Array
SPI	Serial Peripheral Interface
SRAM	Static Random-Access Memory
USB	Universal Serial Bus
VVML	Voice and Vision Machine Learning
AT	Attention
SS	Shoulder Surfing



## 1. Introduction

This document describes User Tracking demo using the CrossLink™-NX Voice and Vision Machine Learning (VVML) platform.

# 2. Functional Description

Figure 2.1 shows the top view of the VVML board used in this demonstration.

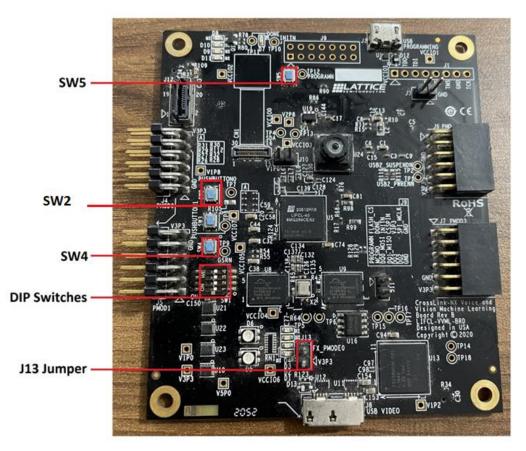


Figure 2.1. VVML Rev-B board - Top View



# 3. Demo Setup

This section describes the demo setup.

## 3.1. Hardware Requirements

- CrossLink-NX Voice and Vision Machine Learning Board, Rev. B
- USB 3.0 A to Micro B cable (To load firmware in FX3 and to run demo using video visualizing tool), USB 2.0 A to Micro B cable (to program Crosslink-NX VVML board)
- Personal computer

## 3.2. Software Requirements

- Lattice Radiant™ Programmer version 3 (Refer to <a href="http://www.latticesemi.com/programmer">http://www.latticesemi.com/programmer</a>)
- Cypress EZ-USB FX3 Software Development Kit (Refer to <a href="https://www.cypress.com/documentation/software-and-drivers/ez-usb-fx3-software-development-kit">https://www.cypress.com/documentation/software-and-drivers/ez-usb-fx3-software-development-kit</a>)
- Video visualizing tool to see output, user can use one of below tool:
- 1. VLC Media Player: https://www.videolan.org/vlc/download-windows.html
- Windows Camera APP: To use windows camera app user must change default webcam if other camera device is connected to system. For more info user can follow steps mentioned in link: <a href="https://answers.microsoft.com/en-us/windows/forum/all/how-to-change-default-webcam-in-windows-10/1e8377c8-4fd5-4e9c-8ab6-67913c5c8e0c.">https://answers.microsoft.com/en-us/windows/forum/all/how-to-change-default-webcam-in-windows-10/1e8377c8-4fd5-4e9c-8ab6-67913c5c8e0c.</a>
- 3. AMCap: http://noeld.com/programs.asp?cat=video.



# 4. Programming the Demo

This document describes the FaceID Demo running process using the Crosslink-NX™ Voice and Vision platform. To Run the demo user will need prebuilt '.mcs' and '.bit' file to program the Crosslink-NX VnV board.

## 4.1. Package Folder Structure

Figure 4.1 shows the demo folders and files after unzipping the package.

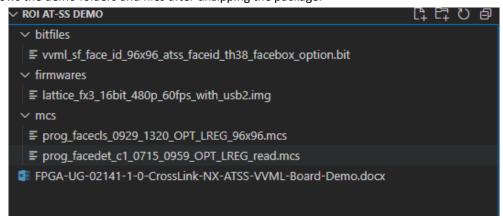


Figure 4.1. Demo Package Folder Structure

#### 4.2. Load Firmware in FX3 I2C EEPROM

To load the firmware:

- 1. Connect jumper J13, user refer to section Functional Description for location of jumper on VVML Board.
- 2. Connect the USB3 port of the CrossLink-NX VVML Board (Rev B) to the PC using the USB3 cable.
- 3. Open the USB Control Centre application. The Cypress FX3 SDK should be installed.
- 4. Press the SW2 button to reset the FX3 chip. Figure 4.2 shows the boot loader device screen.



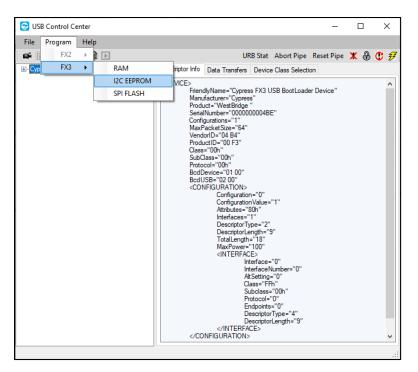


Figure 4.2. Selecting FX3 I2C EEPROM in USB Control Centre

- 5. Select Cypress USB Bootloader.
- 6. Click Program > FX3 > I2C E2PROM.
- 7. Locate and select the FX3 image file for the 640 × 480p 60 Hz 16 bit configuration.
- 8. The Firmware is programmed in the I<sup>2</sup>C E2PROM.
- 9. After the operation is completed, a message acknowledging successful programming is shown at the bottom taskbar.
- 10. Remove jumper J13.
- 11. Power OFF and then power ON the board.
- 12. The FX3 boots from I<sup>2</sup>C E2PROM.

## 4.3. Programming the CrossLink-NX Voice and Vision SPI Flash

#### 4.3.1. Erasing the CrossLink-NX Voice and Vision SRAM Prior to Reprogramming

If the CrossLink-NX device is already programmed (either directly, or loaded from SPI Flash), follow this procedure first to erase the CrossLink-NX SRAM memory before re-programming the SPI Flash. If you are doing this, keep the board powered when reprogramming the SPI Flash (so it does not reload on reboot).

To erase the CrossLink-NX device:

1. Launch Lattice Radiant™ Programmer. In the Getting Started dialog box, select Create a new blank project.



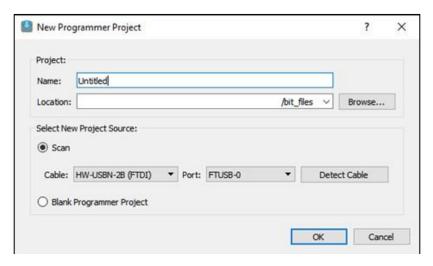


Figure 4.3. Lattice Radiant Programmer Default Screen

- 2. Click OK.
- 3. In the Lattice Radiant Programmer main interface, select LIFCL for Device Family, as shown in Figure 4.4.
- 4. Select LIFCL for Device Vendor, and LIFCL-40 for Device.

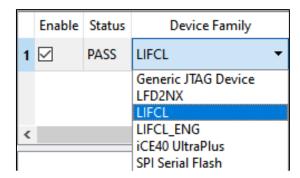


Figure 4.4. Lattice Radiant Programmer- Device Selection

- 5. Right-click and select Device Properties.
- 6. Select JTAG for Port Interface, Direct Programming for Access Mode, and Erase Only for Operation, as shown in Figure 4.5.

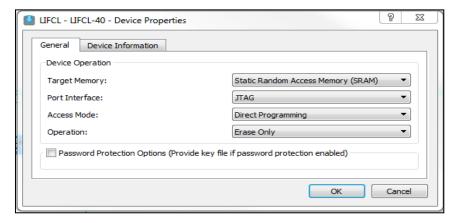


Figure 4.5. Lattice Radiant Programmer – Device Operation

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- 7. Click OK to close the Device Properties dialog box.
- 8. Press and hold SW5 until you see the Successful message in the Lattice Radiant log window.
- 9. In the Radiant Programmer main interface, click the Program 🚇 button to start the erase operation.

#### 4.3.2. Programming the CrossLink-NX Voice and Vision Board

To program the CrossLink-NX Voice and Vision SPI Flash:

- 1. Ensure that the CrossLink-NX Voice and Vision device SRAM is erased by performing the steps in the Erasing the CrossLink-NX Voice and Vision SRAM Prior to Reprogramming section.
- 2. In the Lattice Radiant Programmer main interface, right-click Operation and select Device Properties.
- 3. In the Device Properties dialog box, apply the settings shown in Figure 4.6.

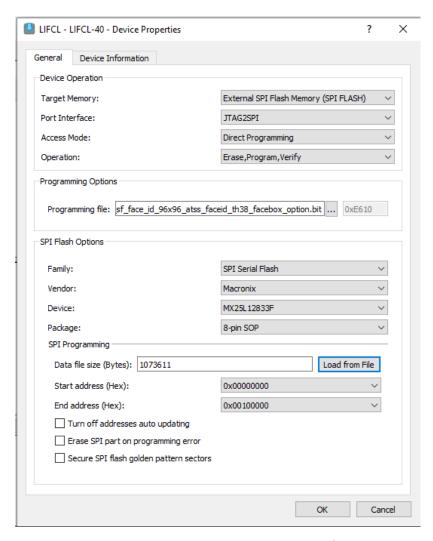


Figure 4.6. Radiant Programmer – Selecting Device Properties Options for CrossLink-NX Flashing

#### Notes:

- In Programming file, browse and select the CrossLink-NX Voice and Vision bit file (\*.bit).
- Click Load from File to update the Data file size (bytes) value.
- Ensure that the following addresses are correct:
  - Start Address (Hex) 0x00000000
  - End Address (Hex) 0x00100000



- 4. Click OK.
- 5. Now press SW5 push button switch before clicking program button in below step and keep it pressed till you see Successful message in Radiant log window.
- 6. Click the Program button to start the programming operation.
- 7. After successful programming, the Output console displays the result, as shown in Figure 4.7.



Figure 4.7. CrossLink-NX Voice and Vision Flashing Switch – SW5 Push Button

## 4.3.3. Programming SensAl Firmware Binary to the CrossLink-NX Voice and Vision SPI Flash

#### 4.3.3.1. Flash SensAl Firmware Hex for Face Detection to Crosslink-NX SPI Flash

To program the CrossLink-NX SPI flash:

- 1. Ensure that the CrossLink-NX device SRAM is erased by performing the steps in the Erasing the CrossLink-NX Voice and Vision SRAM Prior to Reprogramming section before flashing bitstream and sensAl firmware binary.
- 2. In the Lattice Radiant Programmer main interface, right-click the CrossLink-NX row and select Device Properties.
- 3. In the Device Properties dialog box, apply the settings as shown in Figure 4.8.



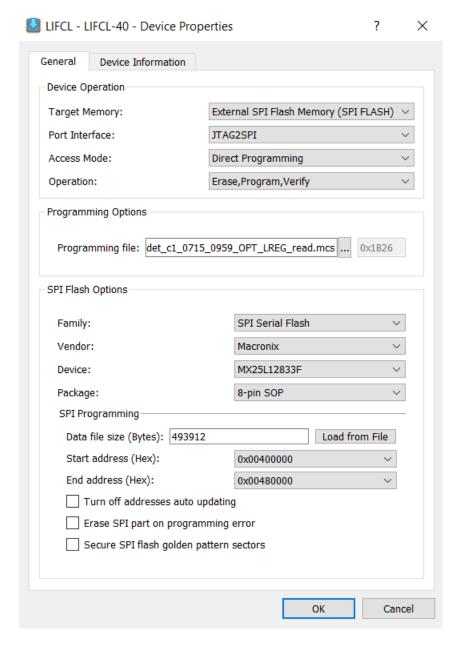


Figure 4.8. Radiant Programmer - Selecting Device Properties Options for CrossLink-NX Flashing

#### Notes:

- In Programming file, browse and select the CrossLink-NX sensAI firmware binary file after converting it to hex (\*.mcs).
- Click Load from File to update the Data file size (bytes) value.
- Ensure that the following addresses are correct:
  - Start Address (Hex) 0x00400000
  - End Address (Hex) 0x00480000
- 4. Click OK.
- Now press SW5 push button switch before clicking program button in below step and keep it pressed till you see Successful message in Radiant log window.
- 6. Click the Program button 🕮 to start the programming operation.



7. After successful programming, the Output console displays the result, as shown in Figure 4.9.



Figure 4.9. Radiant Programmer – Output Console

## 4.3.3.2. Flash SensAl Firmware Hex for User Tracking Classification to Crosslink-NX SPI Flash

To program the CrossLink-NX SPI flash:

- 1. Ensure that the CrossLink-NX device SRAM is erased by performing the steps in Erasing the CrossLink-NX Voice and Vision SRAM Prior to Reprogramming section before flashing bitstream and sensAl firmware binary.
- 2. In the Lattice Radiant Programmer main interface, right-click the CrossLink-NX row and select Device Properties.
- 3. In the Device Properties dialog box, apply the settings as shown in Figure 4.10.



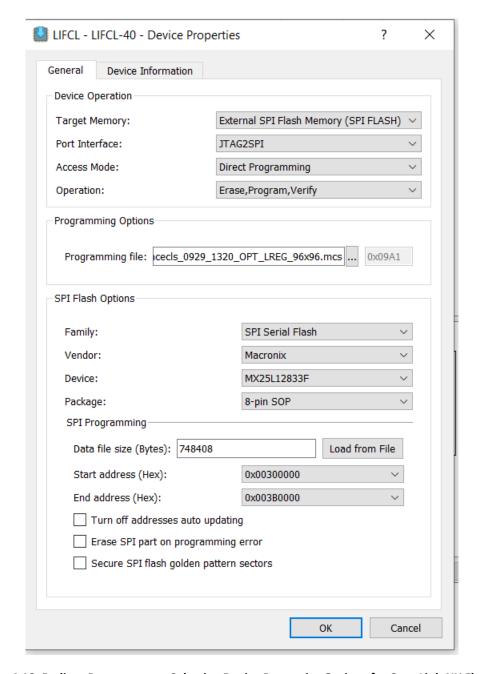


Figure 4.10. Radiant Programmer – Selecting Device Properties Options for CrossLink-NX Flashing

#### Notes:

- In Programming file, browse and select the CrossLink-NX sensAl firmware binary file after converting it to hex (\*.mcs).
- Click Load from File to update the Data file size (bytes) value.
- Ensure that the following addresses are correct:
  - Start Address (Hex) 0x00300000
  - End Address (Hex) 0x003B0000
- 4. Click OK.
- 5. Now press SW5 push button switch before clicking program button in below step and keep it pressed till you see Successful message in Radiant log window.

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FPGA-UG-02158-1.0

- 6. Click the Program button 🎒 to start the programming operation.
- 7. After successful programming, the Output console displays the result, as shown in Figure 4.11.



Figure 4.11. Radiant Programmer - Output Console

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# 5. Running the Demo

- 1. To run the demo:
- 2. Power on the VVML board.
- 3. Make sure that the position of DIP SWITCH is as given below

DIP Switch	State
SWITCH 1	OFF
SWITCH 2	OFF
SWITCH 3	ON
SWITCH 4	ON

- 4. Flash the .bit and .mcs files.
- 5. Connect the VVML board to the PC through the USB3 port.
- 6. Open one of video tool:
- 7. For AMCap video display application and select the FX3 Device as source from under Devices.
- 8. For Windows Camera app disable other camera device if any available and set FX3 as default camera device as mentioned in Load Firmware in FX3 I2C EEPROM.
- 9. For VLC Media player click Media -> Open Capture Device and select video device name as FX3.
- 10. The camera image with green guide lines enabled is displayed in the output Figure 5.1.
- 11. User Tracking output can be interpreted as following:
- Green box: Attentive user
- Blue box: Non-Attentive user
- The right bottom corner shows the Region of Interest i.e. cropped detected faces



Figure 5.1. Running the Demo



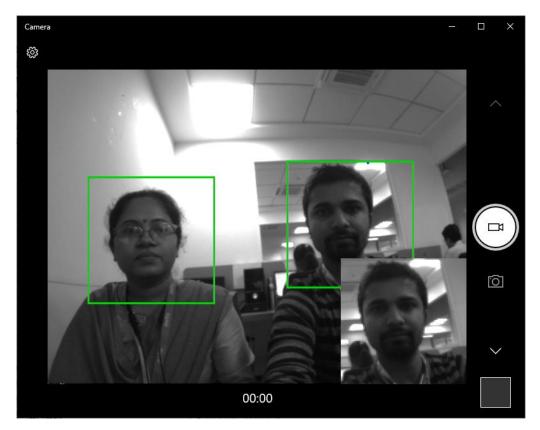


Figure 5.2. Running the Demo

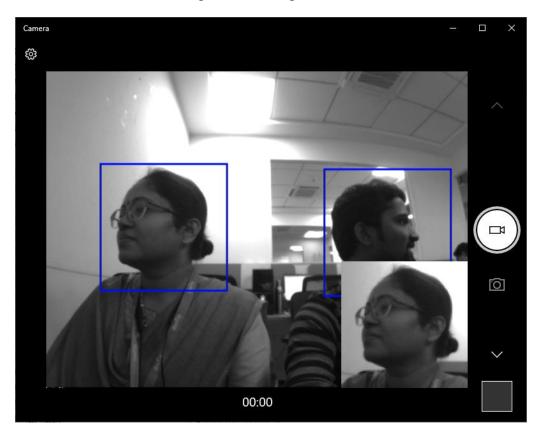


Figure 5.3. Running the Demo



## 5.1. Ideal Conditions for testing the demo

- Distance: Users should be in range of 1.5 to 5 feet distance.
- Descent light is needed to run demo. Too low and direct light from light source may reduce the performance of demo.



# **Technical Support Assistance**

Submit a technical support case through www.latticesemi.com/techsupport.

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# **Revision History**

## Revision 1.0, June 2022

Section	Change Summary
All	Initial release.



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